Ref #	Hits	Search Query	DBs	Default Operat or	Plural s	Time Stamp
L1	94	(EDWARDS-ERIC-C or EDWARDS-ERIC or EDWARDS-ERIC-\$).in.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L2	12440	(camera and (((head or helmet) near mount\$3) or HMD))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06
L3	0	L1 and L2	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L4	19542	(motion near compensat\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06
L5	12469	(pitch and roll and yaw)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L6	13495	(range adj (sensor or detector))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L7	678	(predetermined adj fill)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L8 .	1895	((slave or slaved) with camera)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L9	44356	((vertical and horizontal) with (offset\$4 or shift\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L10	20571	(image near (offset\$4 or shift\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L11	28802	(stereoscopic or (stereo adj scopic))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L12	195974	(time adj delay)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L13	5987	(camera with (((head or helmet) near mount\$3) or HMD))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L14	7062	(camera same (((head or helmet) near mount\$3) or HMD))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L15	0	(Hirose-Michitaka and Yokoyama-Kensuke and Sato-Shin-ichi).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L16	992	(telepresen\$4 or (tele adj presen\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L17	210	(telepresen\$4 or (tele adj presen\$4)).ab.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06
L18	2034	(camera and (((head or helmet) near mount\$3) or HMD)).ab.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L19	800245	((head or helmet or HMD) with (velocity or speed or acceleration or position or location or displacement or movement or rotation or orientation))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06
L20	107	(telepresen\$4 or (tele adj presen\$4)).ti.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

T. C.	50015	. 1	IIO DODII	OD	ON	0007/00/05
L21	52817	motorola.as.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L22	7129	348/42,47,50,51,52,53,94, 115,117,123,129,130,135, 139,142,143,144,148,161, 169,207.11,208.2,208.4,208. 14,211.7,211.8,211.9,211.11, 211.14,376.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L23	2088	359/13,630,631,632,633.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L24	3552	340/901,902,903,904,905, 980.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L25	10026	345/1.1,1.3,7,8,9,156,158, 162,184,427,474,592,595, 620,649.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L26	103	(CANADIAN and SPACE). as.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L27	2	xiphos	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L28	0	(xiphos).as.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L29	15486	(camera near (move or moving or movement))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L30	0	(Hirose-Michitaka and Yokoyama-Kensuke and Sato-Shin-\$).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 . 13:33
L31		(Hirose-Michitaka and Yokoyama-Kensuke).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L32	0	Hirose.in. and "virtual dome"	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L33	0	(Hirose-Michitaka and Yokoyama-Kensuke and Sato-Shin).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L34	0	(Michitaka-Hirose and Kensuke-Yokoyama and Shin-ichi-Sato).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L35	0	(Michitaka-Hirose).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L36	30385	Hirose.in.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON .	2007/08/06
L37	19329	(camera near (move or moving or movement or motion))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L38	93431	((head or halmat or UMD or	US-PGPU	OR	ON	2007/08/06
L36	73431	((head or helmet or HMD or headset or head-set) near (move or moving or movement or motion))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OK	OIN	13:33
L39	244	L2 and L37 and L38	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L40	28	L16 and L9	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L41	0	Hirose.in. and (virtual adj dome)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L42	735	L2 and L37	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

L43	23	L16 and L9 and camera	US-PGPU B;	OR	ON	2007/08/06 13:33
			USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB			
L44	76	L16 and L10	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
Ĺ45	25	L16 and L4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L46	2	L18 and L9	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
`L47	9	L18 and L10	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06

	r ·		<u> </u>	·	T	<u> </u>
L48	3	L18 and L4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06
L49	1	(EDWARDS-ERIC-C\$).in.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L50	4	L26 and L2	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L51	15345	(time near compensat\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L52	32092	(camera near (position or angle or direction or orientation))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33

	T			·		·
L53	8226	("field of view" or FOV)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L54	2	L21 and L2	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L55	16	(Hirose-Michitaka or Yokoyama-Kensuke).in.	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:33
L56	37	L2 and L8	US-PGPU B; USPAT; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06

L57		(US-20030164900-\$).did. or (US-5978015-\$ or US-4028725-\$ or US-5984475-\$ or US-5933125-\$ or US-5684498-\$ or US-5703961-\$ or US-6327381-\$ or US-6317127-\$ or US-6307589-\$ or US-6152854-\$ or US-5980256-\$ or US-5307271-\$ or US-4568159-\$ or US-3836953-\$).did. or (WO-200122149-\$).did.	US-PGPU B; USPAT; DERWEN T	OR	ON	2007/08/06 13:33
L58	0	1 and 2	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:39
L59	53	1 and display	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:40
L60	40	1 and (display and camera)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2007/08/06 13:40

26/07